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(503) 226-7391; Inventor: Nachmanson et al.; Title: NON-DETERMINISTIC TESTING;
Attorney Docket No.: 3382-66933;
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FIG. 1

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FIG. 2

FIG. 3

300

RECEIVE
GRAPH

302

CREATE CHINESE
POSTMAN TOUR

304

SPLIT TOUR
INTO SEQ

306

EXECUTE
SEQUENCES

308

DETERMINE
UNTOUCHED

310

COMPUTE
STRATEGY

312

EXECUTE STRATEGY

314

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FIG. 4

400

APPLICATION
416

VERIFY BEHAVIOR
COVERAGE
414

SPECIFICATION
(ASML)
406

CALCULATE
STRATEGY
412

SPECIFICATION
COMPILER
408

CYCLE/SPLIT
410

404

PROCESSOR
402

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FIG. 5

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FIG. 6

600

```
        Initilalize() {
602       front:=P // P is victory set
604       newfront:={}
606
608       foreach v in P // initialize vertices of victory set
610         foreach i from 0 to n { // n is number of maximum edges allowed
612           Pr(v,i):=1 // vertices of victory set have probability of 1
614           C(v,i):=0 // no edge costs since this is victory set
616           S(v,i):=null // no strategies leave the victory set
618         }

620       foreach v in V-P {
622           for each i from 0 to n {
624           Pr(v,i):=0 // all other vertices initialized with zero probability,
626           C(v,i):=0 //                                cost and strategy
628           S(v,i):=null //
            }
        }
```

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FIG. 7

VERTEX	PROB COST STRATEGY	N = 0... 4				
		0	1	2	3	4
V	PR	1	1	1	1	1
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL
A	PR	0	0	0	0	0
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL
B	PR	0	0	0	0	0
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL
G	PR	0	0	0	0	0
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL
C	PR	0	0	0	0	0
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL
D	PR	0	0	0	0	0
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL

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FIG. 8

800

```
802   StrategyCalculation(n){
804     for (i=1; i<=n; i++){
806       foreach v in front
808         Process(v,i)
810       foreach v in newfront
812         foreach k:=i+1;k<=n;k++ {
814           S(v,k):=S(v,i)
816           Pr(v,k):=Pr(v,i)
818           C(v,k):=C(v,i)
            }

820       Visited+=newfront
822       front:=newfront
824       newfront:={}

        }
      }
```

FIG. 9

900

```
902   Process(vertex v,i){
904      foreach edge entering v {
906         let u=edge.source // u is the source vertex of edge
908         if u is not in P // never exit from P, the victory set
910            if u is deterministic
912               if ImprovingOnEdge( edge,i){
914                  S(u,i):=edge
916                  Pr(u,i):=Pr(v,i-1)
918                  C(u,i):=cost(edge)+C(v, i-1)
920                  newfront:=newfront U {u}  // add u to newfront
                     }
922            else  {//the node edge.source is nondeterministic

924               oldPr=Pr(u,i)
926               oldC= C(u,i)
928               if i>1 then
930                  Pr(u,i)+=p(edge)(Pr(v,i-1)-Pr(v,i-2))
                  else
932                  Pr(u,i)+=p(edge)Pr(v,i-1)

934               C(u,i) = max{cost(e)+ C(e.target,i-1): e exits from u}

936               if( oldPr ≠ Pr(u,i) or oldC ≠ C(u,i))
938                  newfront:=newfront U {u}
                  }
               }
            }

940   bool ImprovingOnEdge(edge, v, i)
         return
942      (Pr(edge.target,i-1),cost(edge)+ C(edge.target,i-1)) <
         (Pr(edge.source,i),C(edge.source,i))
```
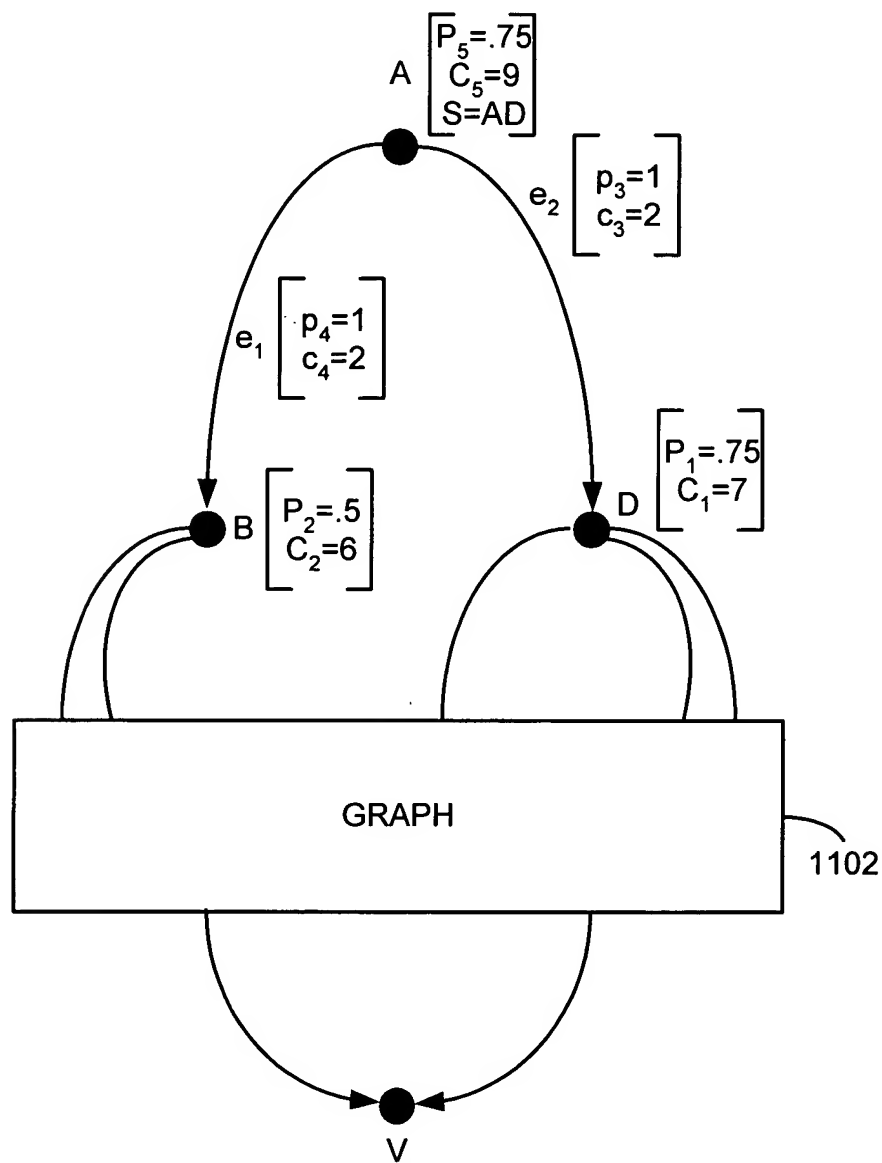
FIG. 10

1000

VERTEX	PROB COST STRATEGY	N = 0… 4				
		0	1	2	3	4
V	PR	1	1	1	1	1
	C	0	0	0	0	0
	S	NULL	NULL	NULL	NULL	NULL
A	PR	0	0	1/2	2/3	3/4
	C	0	0	2	3	4
	S	NULL	NULL	AC	AB	AC
B	PR	0	0	2/3	2/3	2/3
	C	0	0	2	2	2
	S	NULL	NULL	BG	BG	BG
G	PR	0	2/3	2/3	2/3	2/3
	C	0	1	1	1	1
	S	NULL	NULL	NULL	NULL	NULL
C	PR	0	1/2	1/2	1/2	1/2
	C	0	1	1	1	1
	S	NULL	NULL	NULL	NULL	NULL
D	PR	0	0	1/2	1/2	1/2
	C	0	0	2	2	2
	S	NULL	NULL	DC	NULL	NULL

FIG. 11

FIG. 12

```
Traverse(node v,integer k){

   while (k>0){
      k:=k-1
      let e=edge choosen by the environment

      Ti:=choose any Ti starting with e
      cover every edge of Ti
      v:=end of Ti
   }
}
```

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FIG. 13

1300

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FIG. 14